The UF-ECT Applications to different models and realistic bug scenarios.

Teo Price-Broncucia - CU Boulder - June 10, 2024

1

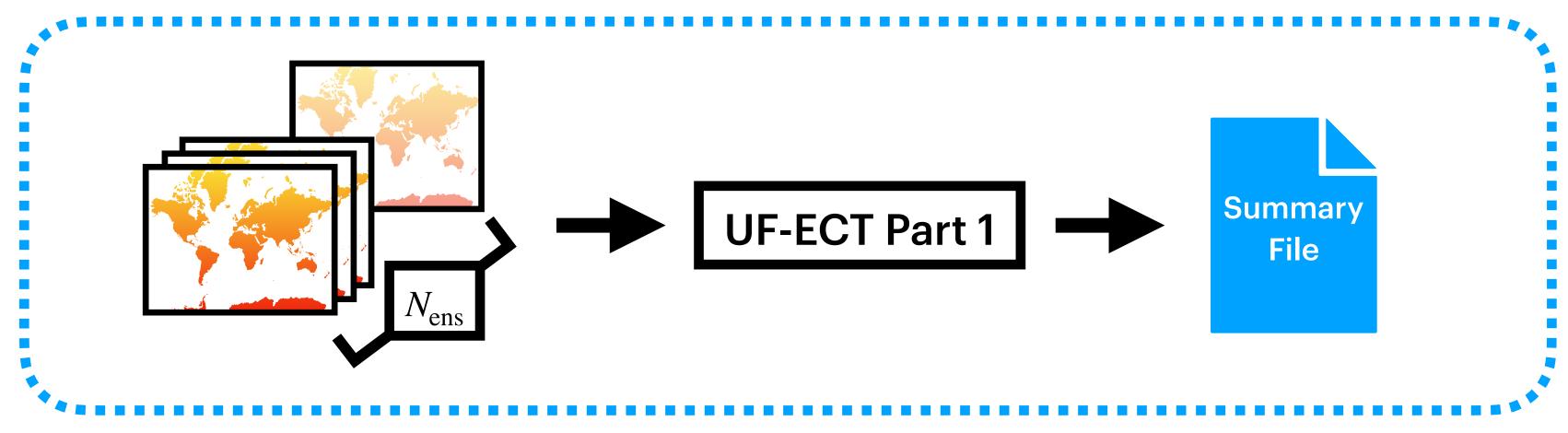
Collaborative Work With:

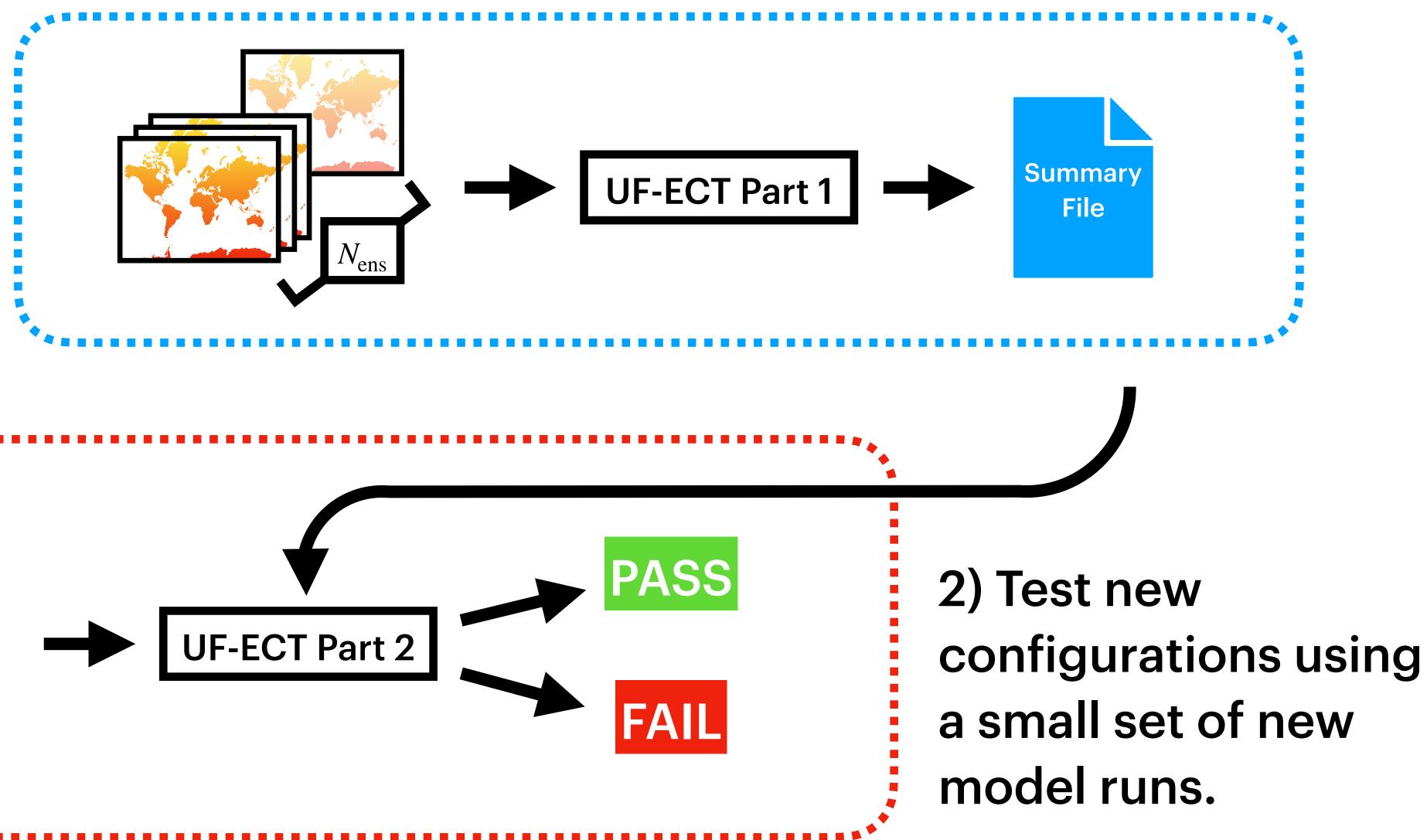
- Allison Baker: NSF-NCAR, CISL-ASP
- Dorit Hammerling: Colorado School of Mines
- Michael Duda: NSF-NCAR, Mesoscale & Microscale Meteorology Lab
- Rebecca Morrison: CU-Boulder

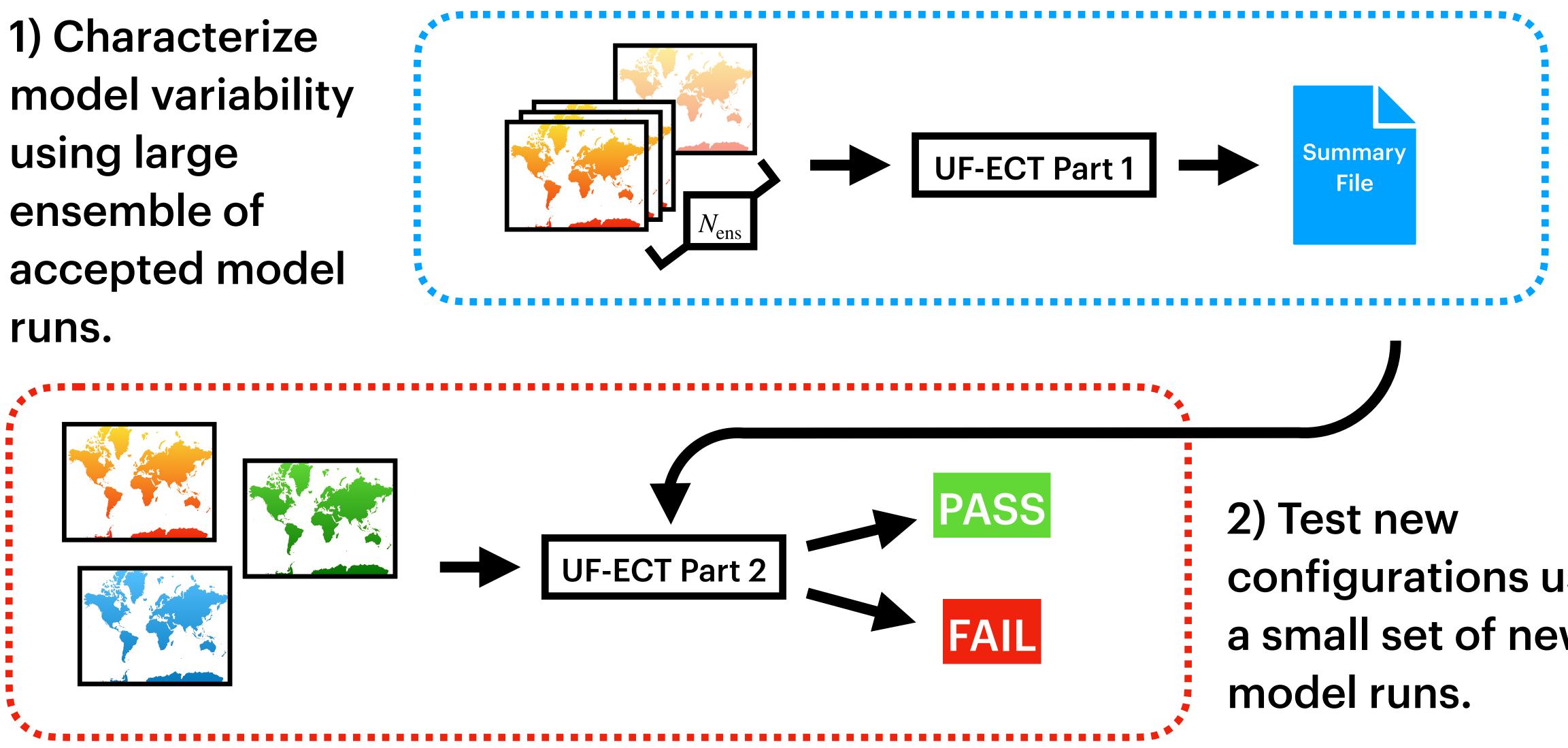
- Ultra-Fast Ensemble Consistency Test
- Designed to identify changes in model outputs exceeding internal model variability.
 - When bit-for-bit equivalence (BFB) is not feasible.
- Require minimal computational expense to test new model configurations.

nce (BFB) is not feasible. ional expense to test new

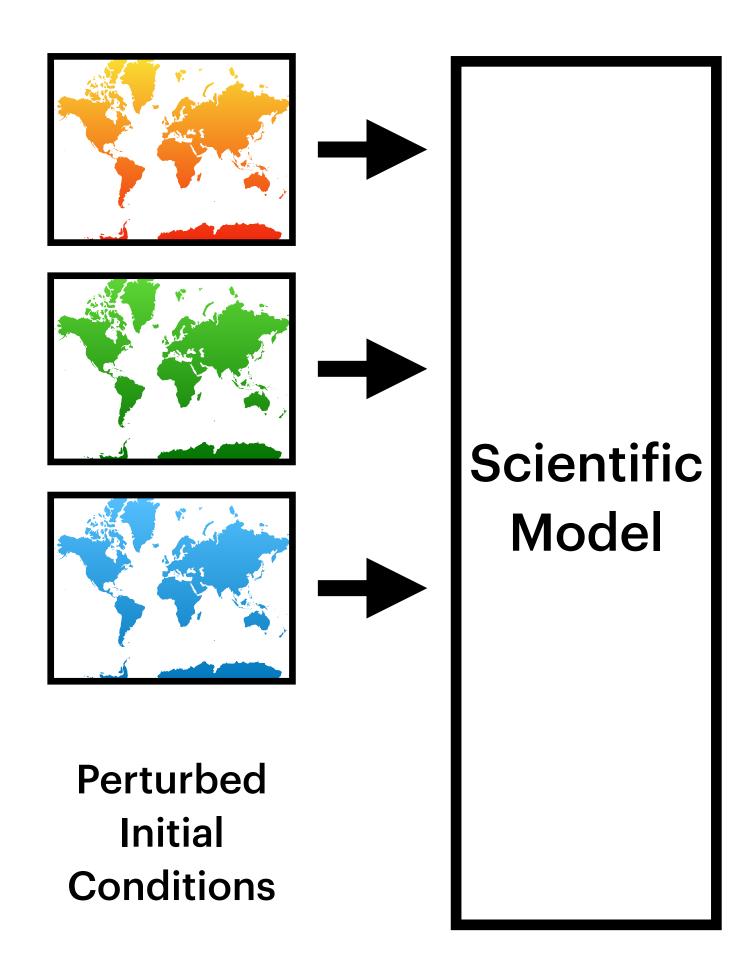
1) Characterize model variability using large ensemble of accepted model runs.

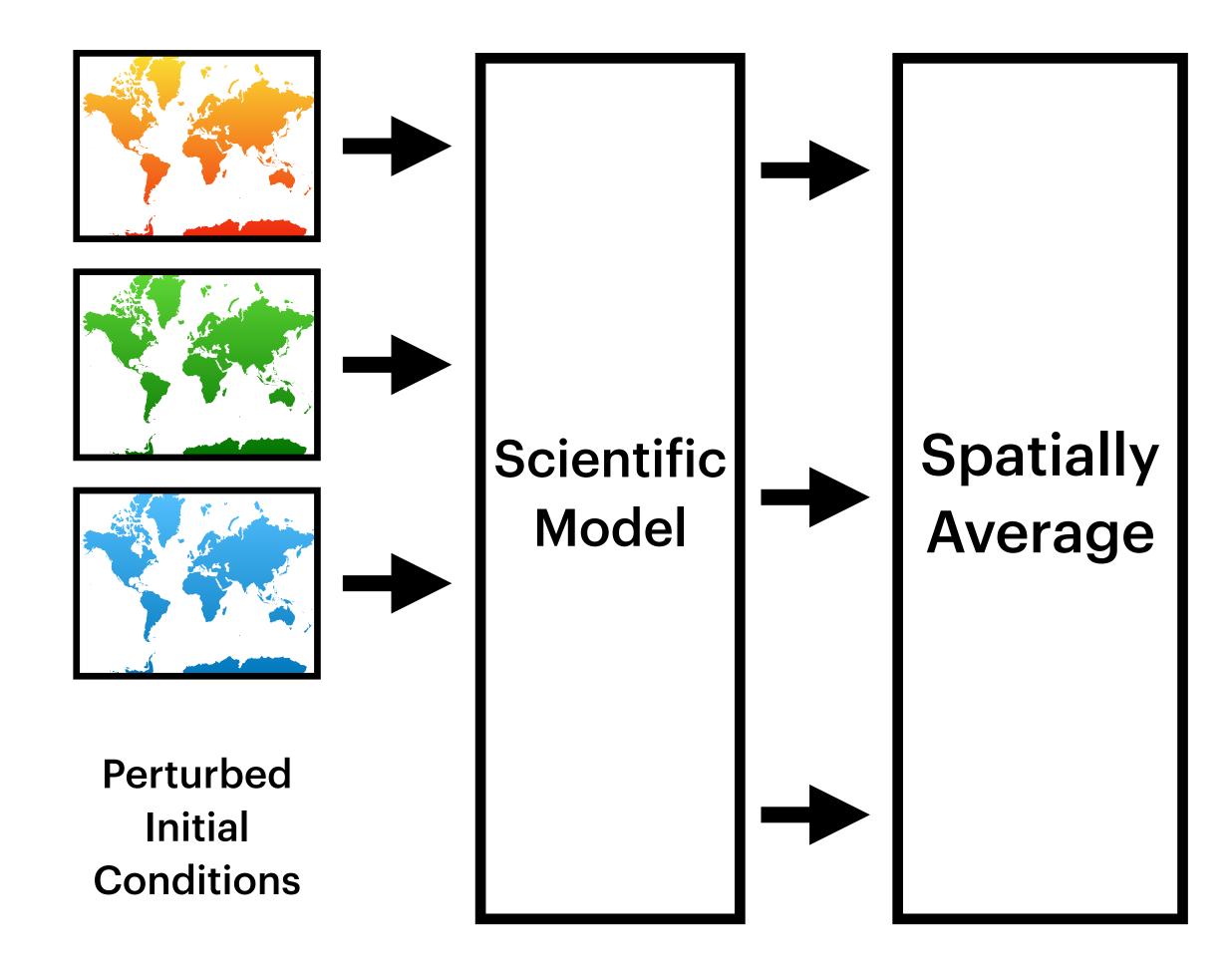


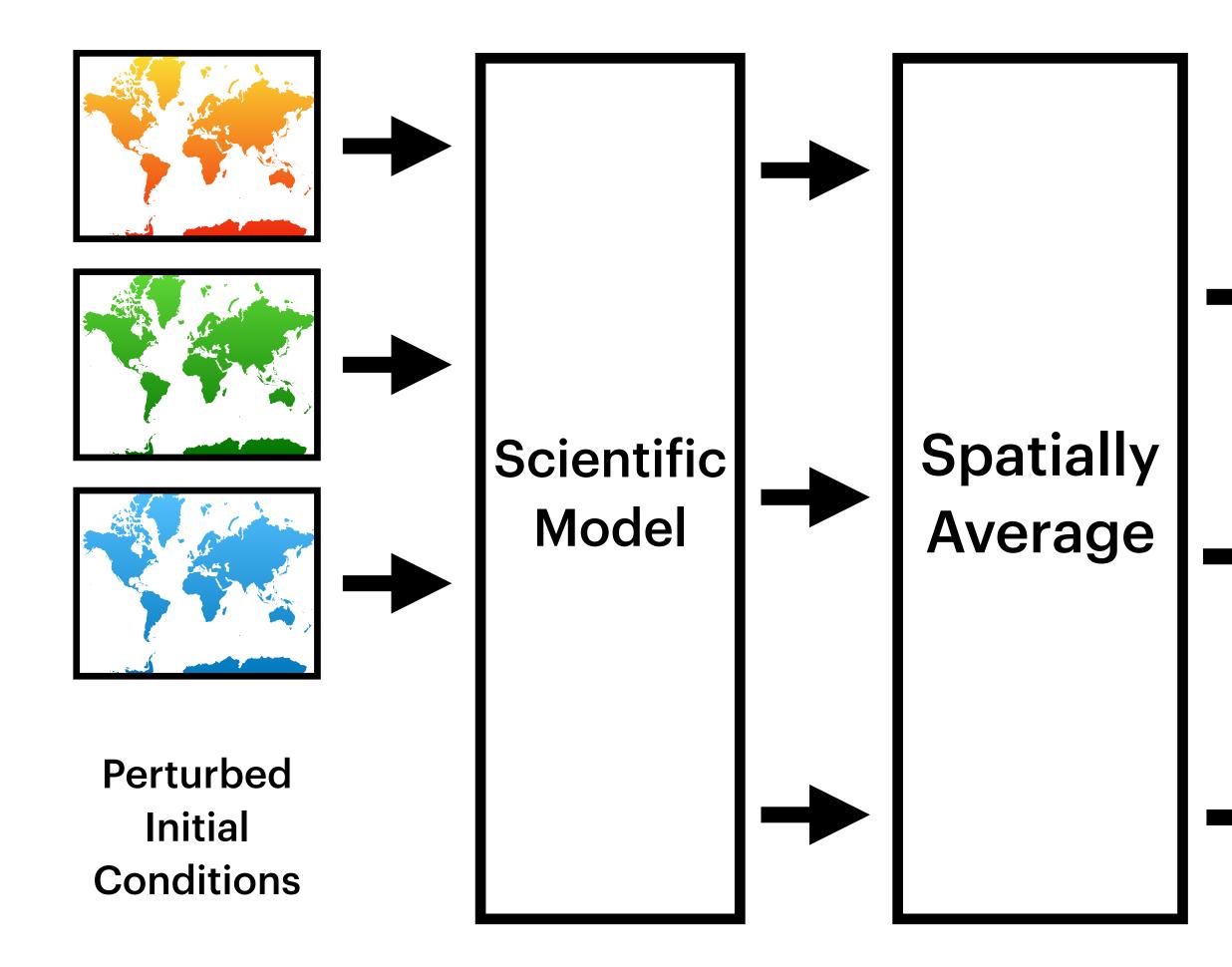


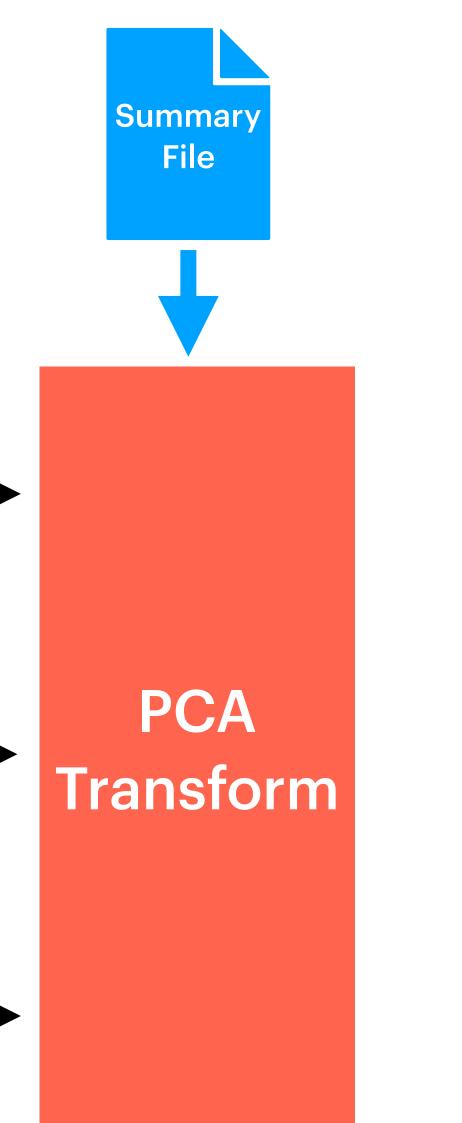


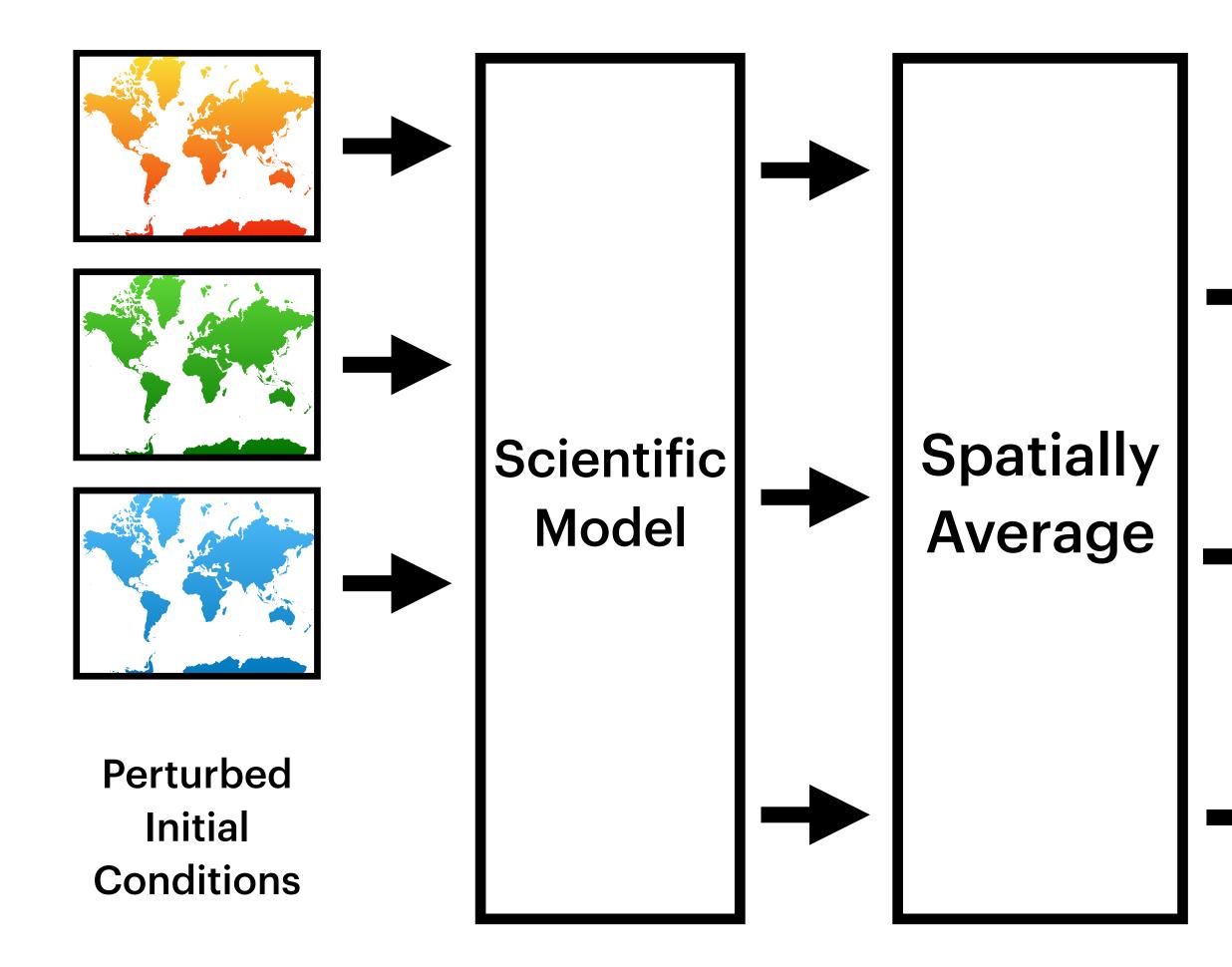


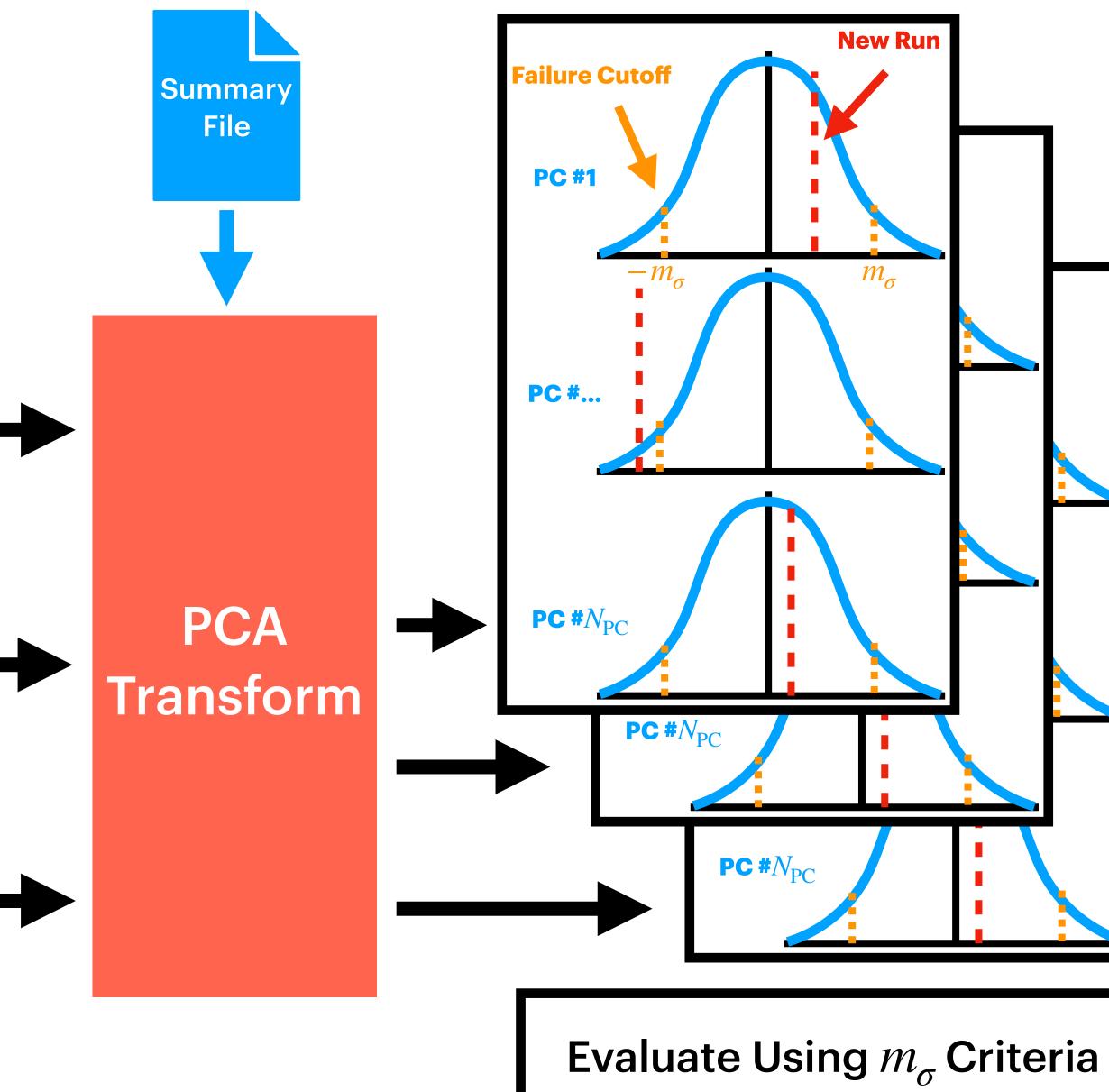


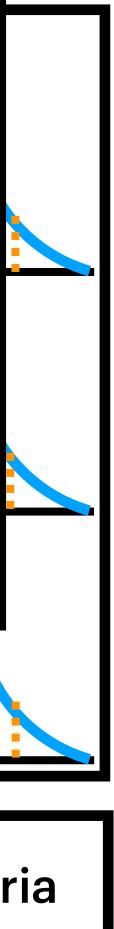


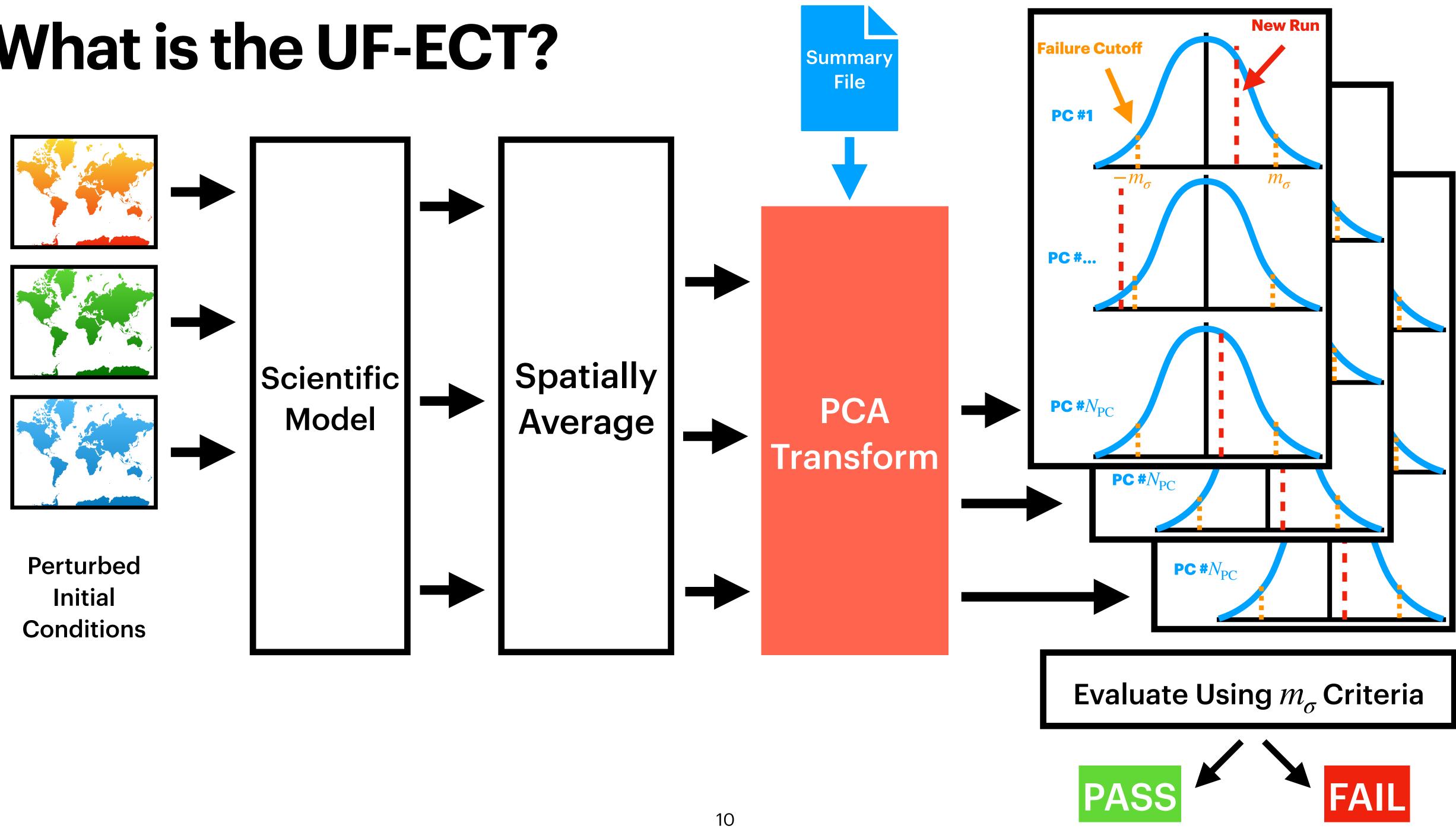




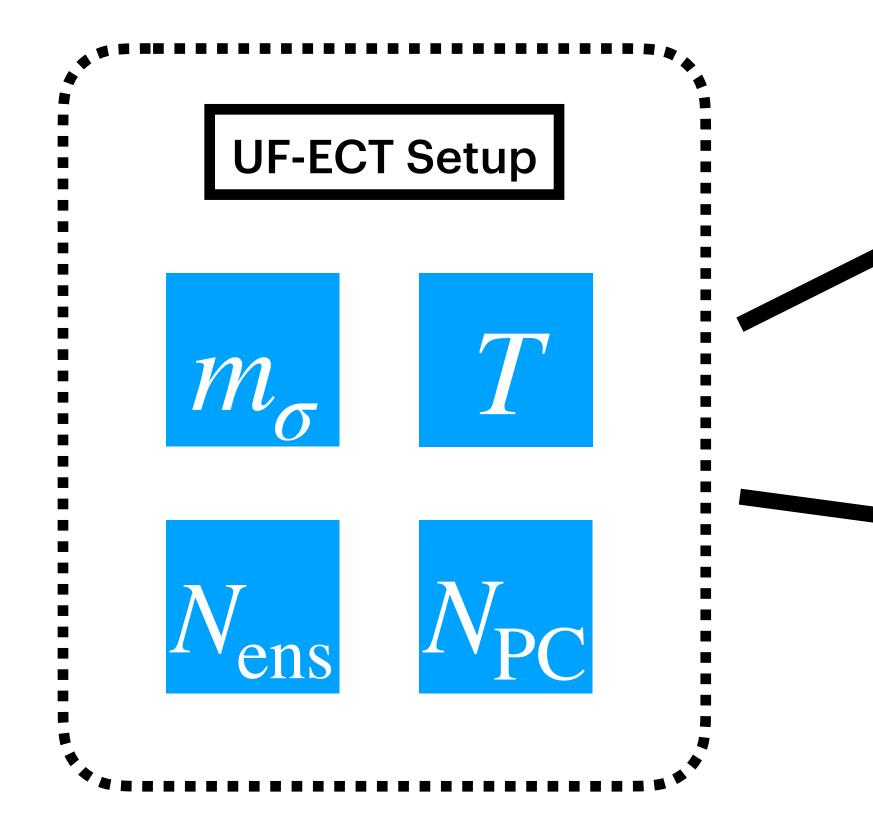


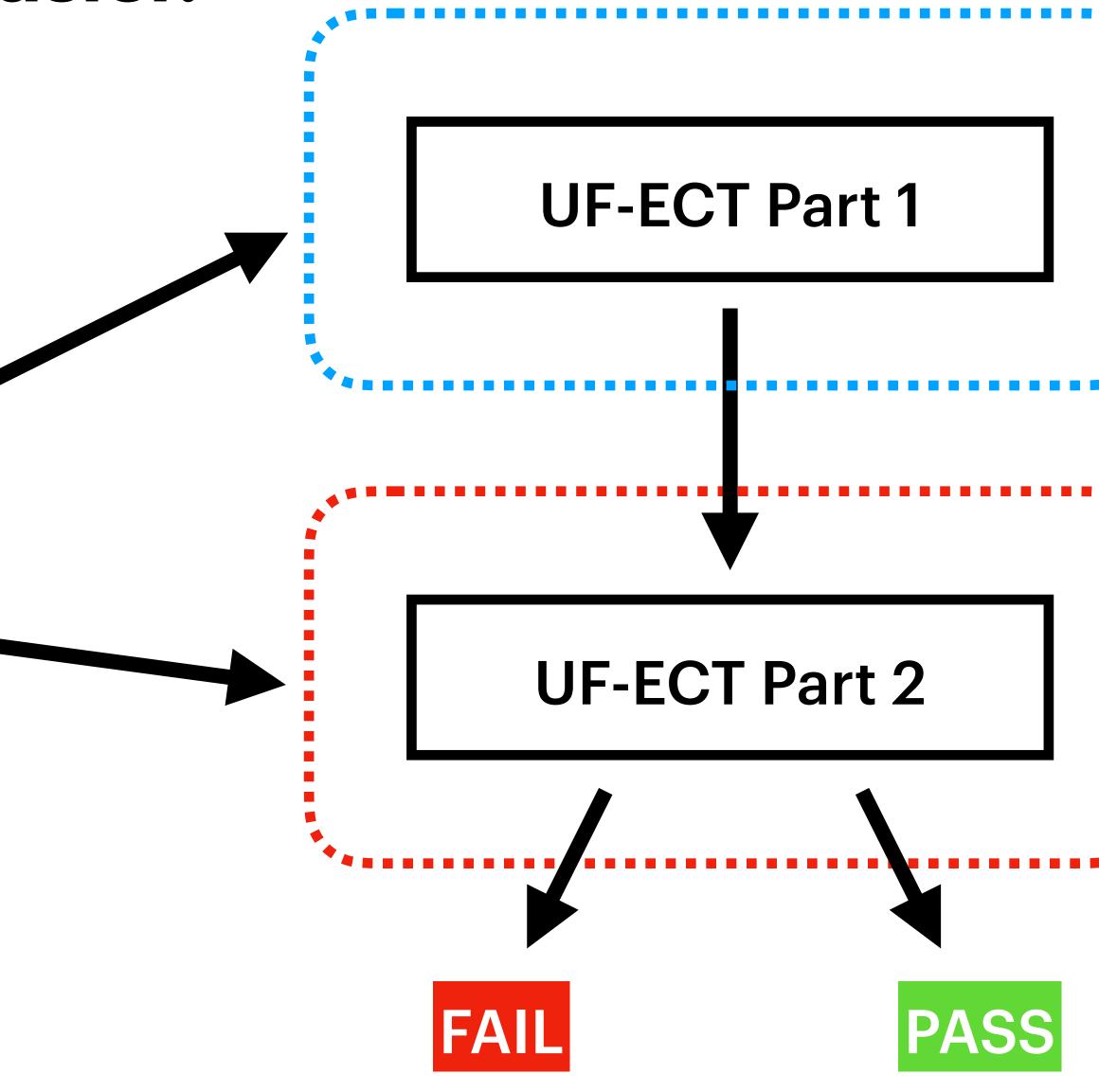






Recent work to make applying the UF-ECT to other models easier.









One testing scenario we ran for MPAS-A involved detecting a fence post error.

- - Also known as an "off-by-one error".

One testing scenario we ran for MPAS-A involved detecting a fence post error.

- One testing scenario we ran for MPAS-A involved detecting a fence post error. Also known as an "off-by-one error".
- MPAS-A contains code to enforce a lower bound on eddy viscosities in the upper-most atmospheric layers (used in a horizontal Smagorinsky type filter).

- One testing scenario we ran for MPAS-A involved detecting a fence post error. Also known as an "off-by-one error".
- MPAS-A contains code to enforce a lower bound on eddy viscosities in the upper-most atmospheric layers (used in a horizontal Smagorinsky type filter).
- Originally this filter was applied across a fixed number of layers (3) but was refactored to use a variable number of layers (N_{filter}).

- One testing scenario we ran for MPAS-A involved detecting a fence post error. • Also known as an "off-by-one error".
- MPAS-A contains code to enforce a lower bound on eddy viscosities in the upper-most atmospheric layers (used in a horizontal Smagorinsky type filter).
- Originally this filter was applied across a fixed number of layers (3) but was refactored to use a variable number of layers (N_{filter}).
- Even without compiler optimizations correct refactoring doesn't yield BFB equivalent results.

A Practical Example

Algorithm 1 Baseline

 $K(N_{ ext{layer}}) = \max\{K(N_{ ext{layer}})\}$ $K(N_{ ext{layer}}-1) = \max\{K(N_{ ext{layer}}-2)\}$

$$V_{
m layer} - 1), \quad 3/3 * \mu \} \ V_{
m layer} - 2), \quad 1/3 * \mu \}$$

A Practical Example: Generalized

Algorithm 1 Baseline

$$\begin{split} &K(N_{\text{layer}}) = \max\{K(N_{\text{layer}}), \quad 3/3 * \mu\} \\ &K(N_{\text{layer}} - 1) = \max\{K(N_{\text{layer}} - 1), \quad 2/3 * \mu\} \\ &K(N_{\text{layer}} - 2) = \max\{K(N_{\text{layer}} - 2), \quad 1/3 * \mu\} \end{split}$$

Algorithm 2 Generalized

$$i \leftarrow (N_{\text{layer}} - N_{\text{filter}} + 1)$$

while $i \leq N_{\text{layer}}$ do
 $K(i) = \max\{K(i), \quad (1.0 - (N_{\text{layer}} - i)/N_{\text{filter}}) * \mu\}$

end while

A Practical Example: Generalized with Bug

Algorithm 1 Baseline

$$\begin{split} &K(N_{\text{layer}}) = \max\{K(N_{\text{layer}}), \quad 3/3 * \mu\} \\ &K(N_{\text{layer}} - 1) = \max\{K(N_{\text{layer}} - 1), \quad 2/3 * \mu\} \\ &K(N_{\text{layer}} - 2) = \max\{K(N_{\text{layer}} - 2), \quad 1/3 * \mu\} \end{split}$$

Algorithm 3 Generalized, with off-by-one error

$$i \leftarrow (N_{\text{layer}} - N_{\text{filter}} + 1)$$

while $i \leq N_{\text{layer}}$ do
 $K(i) = \max\{K(i), \quad (1.0 - (N_{\text{layer}} - i + 1)/N_{\text{filter}}) * \mu\}$
and while

end while

A Practical Example: Can we identify bug?

Algorithm 1 Baseline

$$egin{aligned} &K(N_{ ext{layer}}) = \max\{K(N_{ ext{layer}}), & 3/3*\mu\} \ &K(N_{ ext{layer}}-1) = \max\{K(N_{ ext{layer}}-1), & 2/3*\mu\} \ &K(N_{ ext{layer}}-2) = \max\{K(N_{ ext{layer}}-2), & 1/3*\mu\} \end{aligned}$$

Neither is **BFB**

Algorithm 2 Generalized

 $i \leftarrow (N_{\text{layer}} - N_{\text{filter}} + 1)$ while $i \leq N_{\text{layer}}$ do $K(i) = \max\{K(i), \quad (1.0 - (N_{\text{layer}} - i)/N_{\text{filter}}) * \mu\}$ end while

Algorithm 3 Generalized, with off-by-one error

$$i \leftarrow (N_{\text{layer}} - N_{\text{filter}} + 1)$$

while $i \leq N_{\text{layer}}$ do
 $K(i) = \max\{K(i), \quad (1.0 - (N_{\text{layer}} - i + 1)/N_{\text{filter}}) * \mu$
end while



A Practical Example: Compare fields

(Original - Generalized)

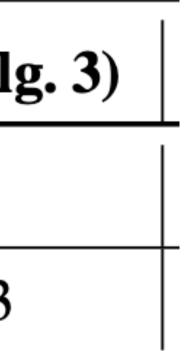
Field	rms(Alg. 1 - Alg. 2)		
u	0.12430		
W	6.20378e-3		

A Practical Example: Compare fields

(Original - Generalized) (Original - Bug)

Field	rms(Alg. 1 - Alg. 2)	rms(Alg. 1 - Alg	
u	0.12430	0.12436	
W	6.20378e-3	6.29749e-3	





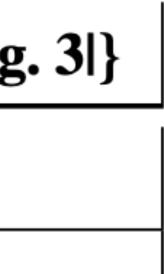
Very similar magnitudes!

A Practical Example: Compare fields

	(Original - Generalized)	(Original - Bug)	(Original - Generalized)	(Original - Bug
Field	rms(Alg. 1 - Alg. 2)	rms(Alg. 1 - Alg. 3)	max{ Alg. 1 - Alg. 2 }	max{ Alg. 1 - Alg
u	0.12430	0.12436	8.37051	10.84282
W	6.20378e-3	6.29749e-3	3.21694e-1	5.98148e-1

Again similar magnitudes.





Can the UF-ECT provide an automated way of identifying these bugs?



A Practical Example: UF-ECT

Generalized

Bug

Algorithm 2

Algorithm 3

Test Failure Rate



100%

• The UF-ECT is an ensemble-based testing framework to identify changes in expensive computer models.

- identify changes in expensive computer models.
- MPAS-A and CESM 3.

• The UF-ECT is an ensemble-based testing framework to

• We have developed a setup framework to make it easier to apply the UF-ECT method to new computer models like

- identify changes in expensive computer models.
- MPAS-A and CESM 3.
- bugs in a fairly automated way with high accuracy.

• The UF-ECT is an ensemble-based testing framework to

• We have developed a setup framework to make it easier to apply the UF-ECT method to new computer models like

UF-ECT can help model developers identify unintentional

Thanks!